



III Year-I Semester	T	P	C
	4	0	3

CONTROL SYSTEMS(RT31043)

PrerequisiteCourse:

Nil

CourseDescriptionandObjectives:

The student will

- Learn the fundamental concepts of Control systems and mathematical modelling of the system.
- Study the concepts of time response and frequency response of the system.
- Understand the basics of stability analysis of the system.

CourseOutcomes:

Upon completion of the course, the student will be able to achieve the following outcomes.

Cos	CourseOutcomes	POs
1	Represent the mathematical model of a system.	3
2	Ability to derive the transfer function of physical systems and determination of overall transfer function using block diagram algebra and signal flow graphs.	3
3	Capability to determine time response specifications of second order systems and to determine error constants.	3
4	Acquires the skill to analyze absolute and relative stability of LTI systems using Routh's stability criterion and the root locus method.	3
5	Capable to analyze the stability of LTI systems using frequency response methods.	3
6	Able to design Lag, Lead, Lag-Lead compensators to improve system performance from Bode diagrams and to represent physical systems as state models and determine the response. Understanding the concepts of controllability and observability.	3

Syllabus:

UNIT I INTRODUCTION

Concepts of Control Systems- Open Loop and closed loop control systems and their differences- Different examples of control systems- Classification of control systems, Feed-Back Characteristics, Effects of feedback. Mathematical models – Differential equations, Impulse Response and transfer functions - Translational and Rotational mechanical systems

UNIT II

TRANSFER FUNCTION REPRESENTATION

Transfer Function of DC Servo motor - AC Servo motor- Synchro transmitter and Receiver, Block diagram representation of systems considering electrical systems as examples -Block diagram algebra – Representation by Signal flow graph - Reduction using mason's gain formula.

UNIT III

TIME RESPONSE ANALYSIS

Standard test signals - Time response of first order systems – Characteristic Equation of Feedback control systems, Transient response of second order systems - Time domain specifications – Steady

state response - Steady state errors and error constants – Effects of proportional derivative, proportional integral systems.

UNIT IV

STABILITY ANALYSIS IN S-DOMAIN

The concept of stability – Routh’s stability criterion – qualitative stability and conditional stability – limitations of Routh’s stability.

Root Locus Technique:

The root locus concept - construction of root loci-effects of adding poles and zeros to $G(s)H(s)$ on the root loci.

UNIT V

FREQUENCY RESPONSE ANALYSIS

Introduction, Frequency domain specifications-Bode diagrams-Determination of Frequency domain specifications and transfer function from the Bode Diagram-Phase margin and Gain margin-Stability Analysis from Bode Plots.

STABILITY ANALYSIS IN FREQUENCY DOMAIN:

Polar Plots, Nyquist Plots Stability Analysis.

UNIT VI

CLASSICAL CONTROL DESIGN TECHNIQUES

Compensation techniques – Lag, Lead, Lead-Lag Controllers design in frequency Domain, PID Controllers. State Space Analysis of Continuous Systems Concepts of state, state variables and state model, derivation of state models from block diagrams, Diagonalization- Solving the Time invariant state Equations- State Transition Matrix and it’s Properties – Concepts of Controllability and Observability.

TEXT BOOKS:

1. Automatic Control Systems 8th edition– by B. C. Kuo 2003– John wiley and son’s.,
2. Control Systems Engineering – by I. J. Nagrath and M. Gopal, New Age International (P) Limited, Publishers, 2nd edition.

REFERENCE BOOKS:

1. Modern Control Engineering – by Katsuhiko Ogata – Prentice Hall of India Pvt. Ltd., 3rd edition, 1998.
2. Control Systems by N.K.Sinha, New Age International (P) Limited Publishers, 3rd Edition, 1998.